

Computing min-cuts in hypergraphs

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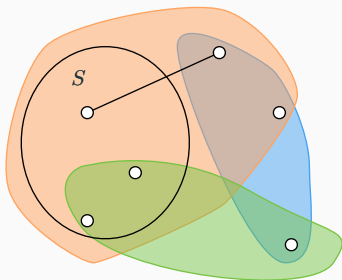
A **hypergraph** $H = (V, E)$ consists of vertices V and edges
 $E \subset \{U \mid U \subset V, |U| \geq 2\}$.

Each edge is assigned with a positive weight $w : E \rightarrow \mathbb{R}_+$.

Cut function

- Edge $e \in E$ **crosses** $S \subset V$, if $e \cap S$ and $e \cap V \setminus S$ are both non-empty.
- $\delta(S)$ is the set of all edges cross S .
- The **cut function** $c : 2^V \rightarrow \mathbb{R}_+$

$$c(S) = \sum_{e \in \delta(S)} w(e)$$



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- A cut S a **st -cut**, if $s \in S$ and $t \in V \setminus S$.
- The max-flow min-cut theorem is relates max- st -flow with min- st -cut (also called **local min-cuts**). It's value is denoted as $\lambda(G, s, t)$.

Why min-cut?

The value of min-cut measures the connectivity of the graph.
Hence min-cuts are useful in clustering and combinatorial optimization.

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- How to find a single min-cut in a graph?
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- A new algorithm for finding ALL min-cuts in graphs.
- How to modify the algorithm to work for hypergraphs?

n is the # of vertices. m is the # of edges.

The fundamental problem: Finding a min-cut

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- Fastest known:

$$\lambda(G) = \min(\lambda(G, s, t), \lambda(G/st))$$

$O(nm + n^2 \log n)$ [Nagamochi & Ibaraki 1992]

The min-cut algorithm

Recurrence relation

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 2. Find MINCUT(G/st).
 3. Return the min of the two.
- $n - 1$ calls to MINCUT.
 - $n - 1$ max flow computation.
 - $O(n^2m)$ again.
 - How to improve this?

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- How? maximum adjacency ordering.

$$d(A, B) = \sum_{e \in \delta(A) \cap \delta(B)} w(e)$$

Adjacency

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v_1, \dots, v_n is a **maximum adjacency ordering** (MA-ordering) if for all $1 \leq i \leq j \leq n$,

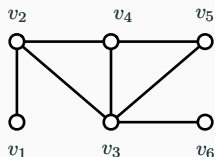
$$d(\{v_1, \dots, v_{i-1}\}, v_i) \geq d(\{v_1, \dots, v_{i-1}\}, v_j).$$

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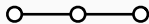
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v_1

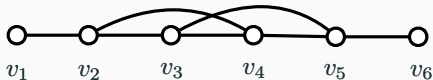
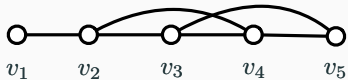
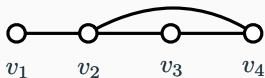
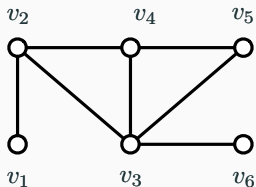


v_1 v_2

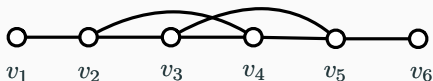
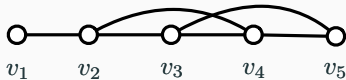
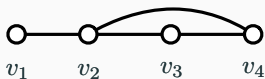
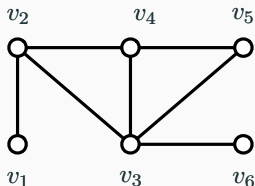


v_1 v_2 v_3

$$d(\{v_1, \dots, v_{i-1}\}, v_i) \geq d(\{v_1, \dots, v_{i-1}\}, v_j)$$



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MA-ordering can be found in $O(m + n \log n)$ time.

$\{v_n\}$ forms a min $v_{n-1}v_n$ -cut.

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Lemma ([Arikati & Mehlhorn 1999])

Given graph $G = (V, E)$ and MA ordering v_1, \dots, v_n . A max $v_{n-1}v_n$ -flow can be found in $O(m)$ time.

A min-cut of a graph can be found in $n - 1 \times$ MA-ordering, so $O(nm + n^2 \log n)$ time.

What about hypergraphs?

- The exact same algorithm works for hypergraphs.
- Different ordering:
 - MA ordering [Klimmek & Wagner 1996]
 - Tight ordering [Mak & Wong 2000]
 - Queyranne ordering [Queyranne 1998]

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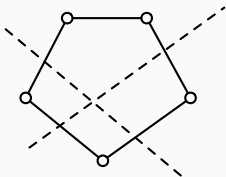
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- $O(n^3)$ space sufficient: $(S, V \setminus S)$ requires $\min(|S|, |V \setminus S|)$ space.
- $\Omega(n^3)$ space required: a cycle, space usage $\sum_{i=1}^{n/2} ni = \Omega(n^3)$.



Finding ALL min-cuts: desirable properties

Find a data structure:

- Small: size is smaller than listing all min-cuts.
- Simple: the structure is simple, so one can query the data structure quickly.

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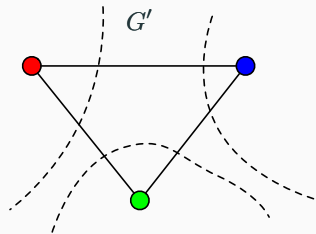
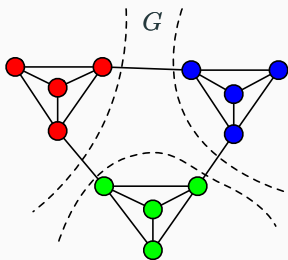
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The best kind of data structure: a smaller, simple graph with the same min-cut structure.

Representation

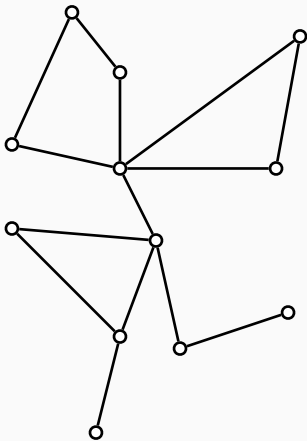
$G' = (V', E')$ is a representation of $G = (V, E)$ if there exist a function $\phi: V \rightarrow V'$, such that

- S is a min-cut in G , then $\phi(S)$ is a min-cut in G' .
- S' is a min-cut in G' , then $\phi^{-1}(S')$ is a min-cut in G .



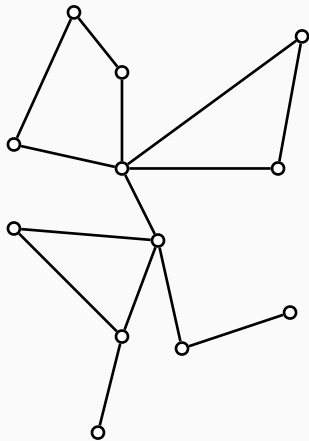
Cactus

A graph is called a cactus if no two cycles share an edge.



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Every graph has a cactus representation. [Karzanov & Timofeev 1986]

Cactus representation: Algorithms, a long history

Large number of work

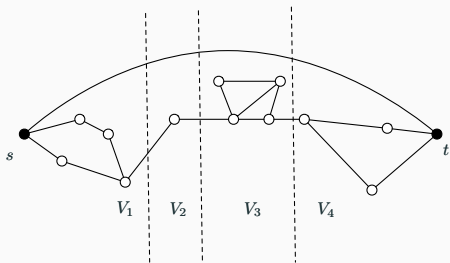
- $O(mn \log(n^2/m))$ [Gabow 1993]
- $O(mn + n^2 \log n + n^* m \log n)$ [Nagamochi & Kameda 1996]
(n^* is # of vertices in the representation)
- $O(mn + n^2 \log n + \gamma m \log n)$ [Nagamochi, Nakao, Ibaraki 2000]
(γ is # of cycles in the representation)
- $O(mn + n^2 \log n)$ [Nagamochi, Nakamura, Ishii 2003]

Cactus representation: The state of the art

An edge e is critical, if e crosses a min-cut.

Theorem ([Nagamochi & Kameda 1996])

If st is an critical edge, then there exists a partition $\{V_1, \dots, V_k\}$ of V , such that $\left\{ \bigcup_{i=1}^j V_i \mid 1 \leq j < k \right\}$ are the set of min- st -cuts.



Can be found in $O(m + n \log n)$ time: MA-ordering.

Cactus representation: Previous method

The partition give us a partial cactus.

Algorithm ALL-MINCUT(G):

1. $A \leftarrow$ cactus of all min- st -cut for some critical edge st .
2. $B \leftarrow$ ALL-MINCUT(G/st).
3. **Cleverly** combine cactus A and B into a cactus for G .

Running time= $n - 1 \times$ MA ordering, same as finding a single min-cut.

Why is the algorithm unsatisfactory

- Complicated

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- Complicated
- Does not generalize to hypergraphs.

Finding cactus representation for graphs

Our approach: a new algorithm

The decomposition framework [Fujishige 1983, Cunningham 1983].

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Remark: Decomposition framework actually handles all (symmetric) submodular functions ([Fujishige 1983]) [Cunningham 1983].

Decomposition: Refinement

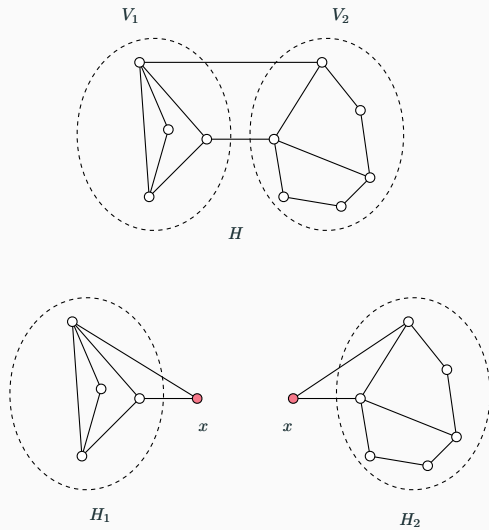
A min-cut with at least two vertices on each side is called a **split**.

Definition

Given a graph G , $\{G_1, G_2\}$ is a **refinement** of G if G_1 and G_2 are graphs obtained through a split (V_1, V_2) and a new marker vertex x as follows.

1. G_1 is G/V_2 , such that V_2 gets contracted to x .
2. G_2 is G/V_1 , such that V_1 gets contracted to x .

Example of a refinement



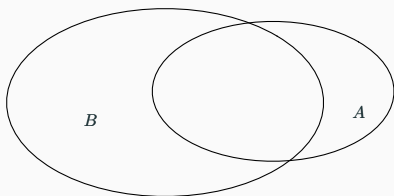
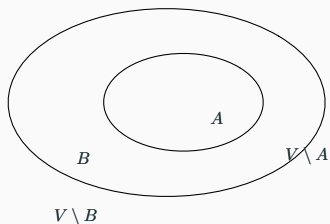
Definition

A set of graphs $\mathcal{D} = \{G_1, \dots, G_k\}$ is a **decomposition** of G if it is obtained from $\{G\}$ by replacing an element by its refinements.

Two decomposition are **equivalent** if they are the same up to relabeling marker vertices.

Crossing

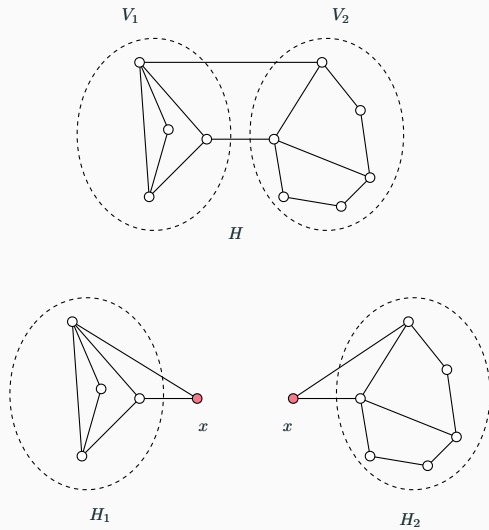
Two cuts $(A, V \setminus A)$ and $(B, V \setminus B)$ are **crossing** if $A \cap B$, $A \setminus B$ and $B \setminus A$ are all non-empty.



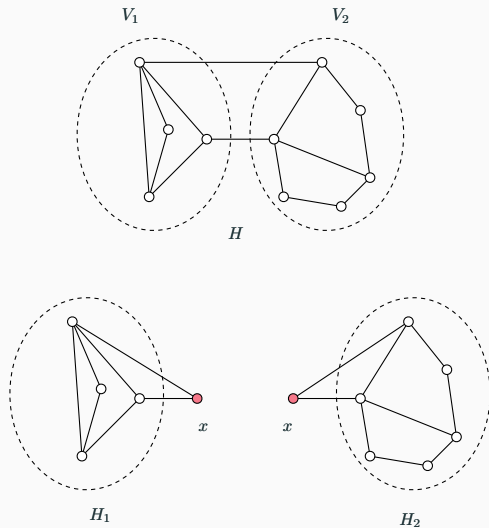
If $(A, V \setminus A)$ and $(B, V \setminus B)$ are non-crossing, then contract A or B **preserves** the other cut.

A split is **good** if no min-cut crosses it.

Refinement preserves cuts



Refinement preserves cuts

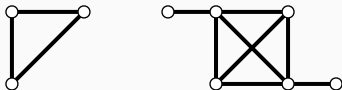


The min-cut in H_1 and H_2 are the min-cuts in H .

**Refine through good splits preserves all
min-cuts.**

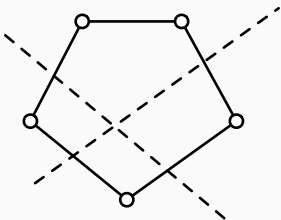
Definition

A graph G is **prime** if it does not contain any split.



Good splits and cycles

There exist graphs that are **not** prime but have no good splits.



Theorem

A graph without any good split is either a prime or a cycle.

Standard decomposition

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A standard decomposition is **minimal**, if it is not a refinement of any other standard decomposition.

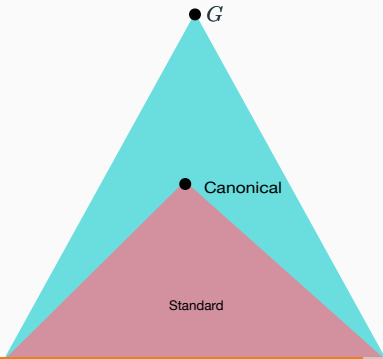
Canonical decomposition

Theorem ([Fujishige 1983,Cunningham 1983])

There exist a unique minimal standard decomposition.

Such decomposition is called the **canonical decomposition**.

Canonical decomposition is what we want: obtained through only applying good splits.



Properties of the canonical decomposition

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- Recover a cactus representation from a canonical decomposition is easy: $O(n)$ time. [Cheng 1999]

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New Goal: Find the canonical decomposition.

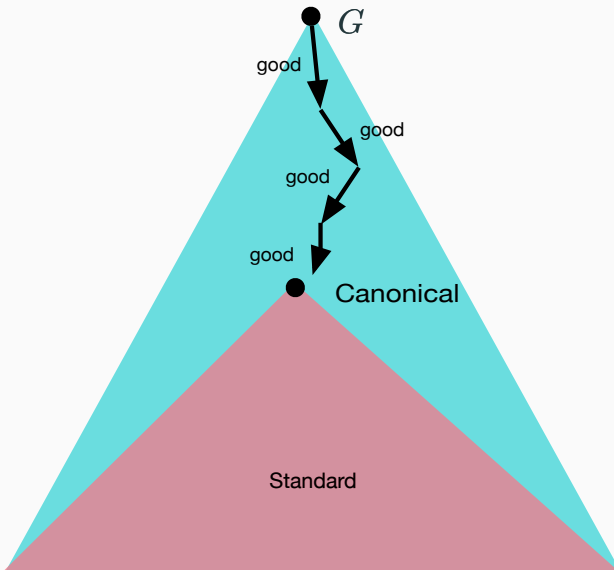
Algorithm, first attempt

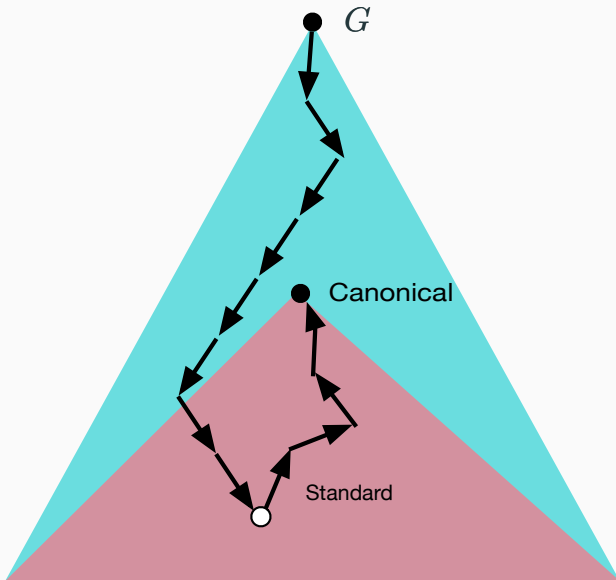
1. Find a good split.
2. Produce a refinement $\{G_1, G_2\}$ using the good split.
3. Recurse on G_1 and G_2 .

Algorithm, first attempt

1. Find a good split.
2. Produce a refinement $\{G_1, G_2\}$ using the good split.
3. Recurse on G_1 and G_2 .

Algorithm running time are dominated by finding $O(n)$ good splits.
Finding a good split is no easier than finding a min-cut.





Algorithm, second attempt

Merge: $\{G_1, \dots, G_k\}$ a decomposition of G , G_1 and G_2 shares a marker vertex. Find a decomposition $\{G', G_3, \dots, G_k\}$ of G , where $\{G_1, G_2\}$ is a refinement of G' .

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1. Find any standard decomposition.
2. Merge elements in the decomposition while maintaining a standard decomposition.

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Second operation is $O(nm)$ time:

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2. Check if merge maintains a standard decomposition.

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New Goal: Find a standard decomposition.

How to find a standard decomposition

Idea: We don't have to always apply refinement all the time. Any progress is fine.

How to find a standard decomposition

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For fixed $s, t \in V$, either there is a split that separates s and t (called a ***st-split***). Or we can contract s and t .

Split oracle

Problem

Given G and the min-cut value λ , outputs either a split in G or a pair of vertices $\{s, t\}$ such that there is no st -split in G .

An algorithm solve the above problem is called a **split oracle**.

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An algorithm solve the above problem is called a **split oracle**.

If we have a fast split oracle, then we can solve the problem.

1. Apply the split oracle on G .
2. If the oracle returns a split, find a refinement of H and recurse on both sides.
3. Otherwise, the oracle output a pair s, t . Contract s and t and recurse.

Implement a split oracle

Theorem

A split oracle can be implemented in $O(m + n \log n)$ time.

Sketch

- Use MA-ordering to find a max st -flow for some s and t .
- Enumerate at most 3 min st -cuts using the maximum flow. It either finds a split or decide there is none. [Provan & Shier 1996]

The reductions

1. cactus representation:

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The reductions

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4. split oracle: MA-ordering $O(m + n \log n)$.

Total running time: $O(nm + n^2 \log n)$. Same as finding a single min-cut.

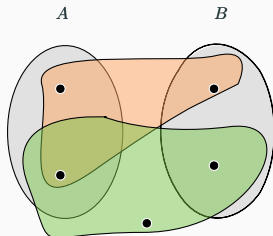
What about hypergraphs?

Our algorithm almost work for hypergraphs. Just a few small changes.

1. We need to use tight ordering instead of MA-ordering.
2. There are non-cycles that also doesn't have any good split.
3. Cactus is not the right representation.

Modification 1: Tight adjacency and tight ordering

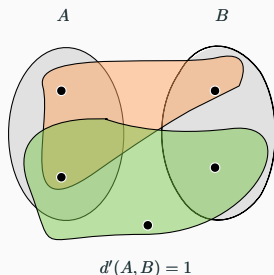
$$d'(A, B) = \sum_{\substack{e \in \delta(A) \cap \delta(B) \\ e \subseteq A \cup B}} w(e)$$



$$d'(A, B) = 1$$

Modification 1: Tight adjacency and tight ordering

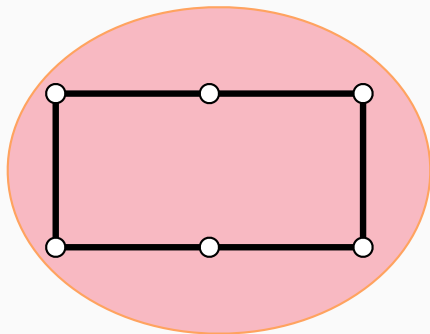
$$d'(A, B) = \sum_{\substack{e \in \delta(A) \cap \delta(B) \\ e \subseteq A \cup B}} w(e)$$



v_1, \dots, v_n is a **tight ordering** (MA ordering) if for all $1 \leq i \leq j \leq n$,

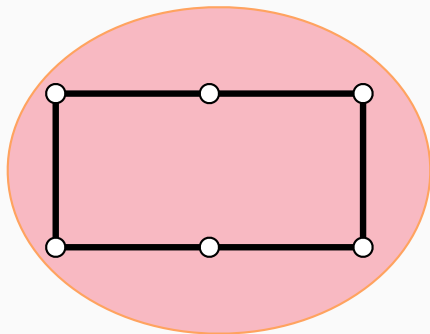
$$d'(\{v_1, \dots, v_{i-1}\}, v_i) \geq d'(\{v_1, \dots, v_{i-1}\}, v_j).$$

Modification 2: Solid polygons



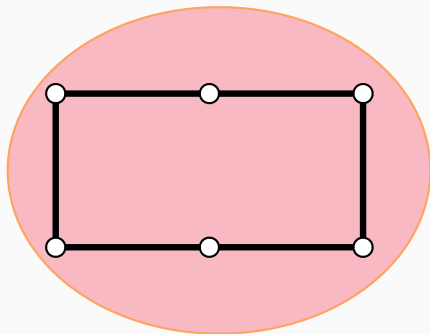
A hypergraph is a **solid polygon** if it consist of a (possibly 0 weight) cycle and a (possibly 0 weight) hyperedge covering all vertices.

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Modification 2: Solid polygons

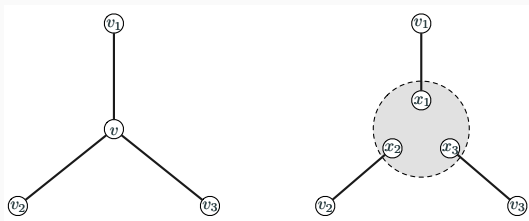


A hypergraph is a **solid polygon** if it consist of a (possibly 0 weight) cycle and a (possibly 0 weight) hyperedge covering all vertices. Hypergraphs with no good splits are either primes or solid polygons. A **standard decomposition** consist of **primes** and **solid polygons**.

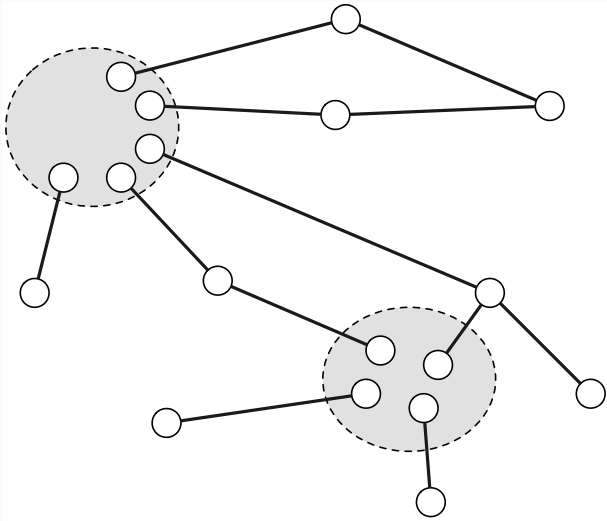
Modification 3: Hypercactus

Definition

A hypergraph is called a **hypercactus** if it can be obtained through the following operations from a cactus: Split the edges incident to a star, and “blow up” the vertex into a hyperedge.



Modification 3: Hypercactus Example



Modification 3: Hypercactus representation

Theorem ([Cheng 1999, Fleiner & Jordán 1999])

Every hypergraph have a hypercactus representation.

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Every hypergraph have a hypercactus representation.

Remark: Fleiner & Jordán actually showed there is a hypercactus representation for all symmetric submodular functions.

All hypergraph min-cuts can be computed in the same running time as finding a single min-cut.

Thank you!